

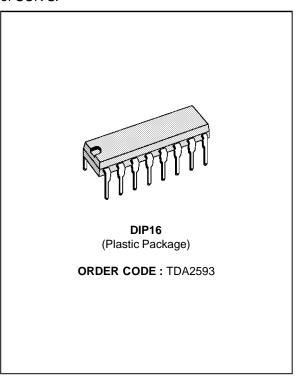
TDA2593

SYNCHRO AND HORIZONTAL DEFLECTION CONTROL FOR COLOR TV SET

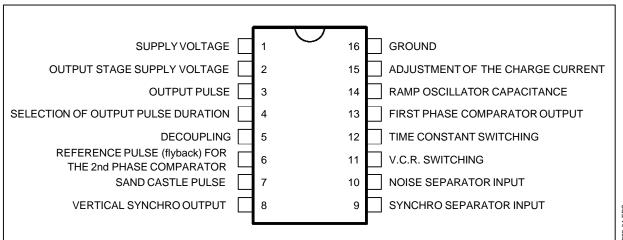
- LINE OSCILLATOR (two levels switching)
- PHASE COMPARISON BETWEEN SYN-CHRO-PULSE AND OSCILLATOR VOLTAGE Ø 1, ENABLED BY AN INTERNAL PULSE, (better parasitic immunity)
- PHASE COMPARISON BETWEEN THE FLY-BACK PULSES AND THE OSCILLATOR VOL-TAGE Ø 2
- COINCIDENCE DETECTOR PROVIDING A LARGE HOLD-IN-RANGE
- FILTER CHARACTERISTICS AND GATE SWITCHING FOR VIDEO RECORDER AP-PLICATION
- NOISE GATED SYNCHRO SEPARATOR
- FRAME PULSE SEPARATOR
- BLANKING AND SAND CASTLE OUTPUT PULSES
- HORIZONTAL POWER STAGE PHASE LAG-GING CIRCUIT
- SWITCHING OF CONTROL OUTPUT PULSE WIDTH
- SEPARATED SUPPLY VOLTAGE OUTPUT STAGE ALLOWING DIRECT DRIVE OF SCR'S CIRCUIT
- SECURITY CIRCUIT MAKES THE OUTPUT PULSE SUPPRESSED WHEN LOW SUPPLY VOLTAGE

DESCRIPTION

The TDA2593 is a circuit intended for the horizontal deflection of color TV sets, supplied with transistors or SCR'S.



PIN CONNECTIONS



2593-01.EPS

September 1993 1/6

MAIN CHARACTERISTICS

Symbol	Parameter	Тур.	Unit
V(1–16)	Supply Voltage	12	V
l(1)	Supply Current	30	mA
NPUT SIGNAL	S	•	•
V(9-16) (pp)	Synchro Separator Input Voltage	3 to 4	V
V(10-16) (pp)	Noise Separators Input Voltage	3 to 4	V
V(4-16) V(4-16) V(4-16)	Control Voltage of the Output Pulse Switching Circuit $t = 7 \mu s$ (thyristor) $t = 14 \mu s + t_d$ (transistor) $t = 0 (V(3-16) = 0)$	9.4 to V(1–16) 0 to 3.5 5.4 to 5.6	V V V
OUTPUT SIGN	ALS		
V(8-16) (pp)	Frame Synchro Pulse	11	V
V(7-16) (pp)	Sandcastle Pulse	11	V
V(3-16) (pp)	Horizontal Driver Stage Control Pulse	10.5	V

ABSOLUTE MAXIMUM RATINGS (Maximum Ratings according to CEI 134 Datasheet)

Symbol	Parameter	Value	Unit
V(1-16)	Supply Voltage to Pin 1	13.2	V
V(2-16)	Supply Voltage to Pin 2	18	V
V(4-16)	Voltage to Pin 4	13.2	V
V(9-16)	Voltage to Pin 9	±6	V
V(10–16)	Voltage to Pin 10	±6	V
V(11–16)	Voltage to Pin 11	13.2	V
$I_{2M} = -I_{3M}$	Current ai Pins 2 and 3 (with thyristor)	650	mA
$I_{2M} = I_{3M}$	Current ai Pins 2 and 3 (with transistor)	400	mA
I(4)	Current to Pin 4	1	mA
I(6)	Current to Pin 6	±10	mA
I(7)	Current to Pin 7	-10	mA
I(11)	Current to Pin 11	2	mA
P _{tot}	Power Dissipation	800	mW
T _{oper}	Operating Ambient Temperature	-20, +70	°C
T _{stg}	Storage Temperature	-25, +125	°C

ELECTRICAL OPERATING CHARACTERISTICS

 $(T_{amb} = 25^{\circ}C, V_1-V_{16} = 12V, unless otherwise specified)$

Symbol	Parameter	Min.	Тур.	Max.	Unit
V _{9–16}	Input Signals Synchro Separator (Pin 9) Input Threshold Voltage		0.8		V
l ₉	Input Threshold Current			5	μΑ
l ₉	On-state Input Current		5 to 100		μΑ
l ₉	Disconnect Input Current	100	150		μΑ
l ₉	Off-state Input Current ($V_{9-16} = -5V$)			- 1	μΑ
V ₉	Video Input Signal (positive synchro pulses) (note 1)		3 to 4		V_{PP}
V ₁₀₋₁₆	Noise Separator (Pin 10) Input Threshold Voltage		1.4		V

Note: 1. Allowed range 1 to 7V



ELECTRICAL OPERATING CHARACTERISTICS

 $(T_{amb}=25^{o}C,\,V_{1}\text{--}V_{16}=12V$, unless otherwise specified)

Symbol	Parameter	Min.	Тур.	Max.	Unit
I ₁₀	Input Threshold Current	100	150		μΑ
I ₁₀	Input Current		5 to 100		μΑ
I ₁₀	Off-state Input Current ($V_{10-16} = -5V$)			- 1	μΑ
V ₁₀	Video Input Signal (positive synchro pulses) (note 1)		3 to 4		V_{PP}
V ₁₀	Allowed superimposed parasitic signal			7	V
V ₆₋₁₆	Fly-back Pulse (Pin 6) Input Threshold Voltage		1.4		V
V ₆	Input Limitation Level		-0.7 and +1.4		V
l ₆	Input Current	0.01	1	2	mA
V ₄₋₁₆			9.4 to V _{1–16} 0 to 3.5 5.4 to 6.6		V V V
I(4)	Input Current $ \begin{array}{ll} t = 7 \; \mu s \; (thyristor) \\ t = 14 \; \mu s \; + t_j \; (transistor) \\ t = 0 \; (V_{3-16} = 0) \end{array} $	200 200	0		μΑ μΑ μΑ
V _{11–16}	Video Recorder Switch (Pin 11) Input Voltage (Pin 11 low level) (Pin 11 to + Vcc)		0 to 2.5 9 to V _{1–16}		V V
I ₁₁	Input Current (Pin 11 low level) (Pin 11 to + V _{CC})			200 2	μA mA
V ₈₋₁₆	Output Signals Frame Synchro Pulses (positive) (Pin 8) Output Voltage (peak value)	10	11		V
R ₈	Output Impedance		2		kΩ
t _{on}	Delay Between Leading Edge of Input Signal and Leading Edge of Output Signal		15		μs
t _{off}	Delay Between Trailing Edge of Input Signal and Trailing Edge of Output Signal		15		μs
SANDCAS	TLE PULSE (POSITIVE) (PIN 7)				
V ₇₋₁₆	Output Voltage (peak valve)	10	11		V
R ₇	Output Impedance		70		Ω
l ₇	Output Current During Trailing Edge		2		mA
t ₇	Sandcastle Pulse Width (V ₇ = 7 V)	3.7		4.3	μs
Δ_{t}	Phase Between Middle Input Synchro Pulse and Leading Edge of Sandcastle Pulse (V ₇ = 7 V)	2.15		3.15	μs
FLY-BACK	BLANKING PULSE (PIN 7)				
V _{7–16}	Output Voltage (peak value)	4		5	V
R ₇	Output Impedance		70	-	Ω
I ₇	Output Current During Trailing Edge		2		mA
	PULSE FOR HORIZONTAL DRIVER (POSITIVE) (PIN 3)	1	ı		
V ₃₋₁₆	Output Voltage (peak value)		10.5		V
R ₃	Output Impedance (leading edge) (trailing edge)		2.5 20		ΩΩ
t ₃	Control Pulse Width $V_4 = 9.4 \text{ to } V_{1-16}$ $V_4 = 0 \text{ to } 4V \text{ (note 3)}$	5.5	14 + t _c	8.5	μs μs
V ₁₋₁₆	Control pulse is disabled for		4		V
	•		I .		

Notes: 1. Allowed range 1 to 7V 2. Or Pin 4 not connected. 3. With t_r = 12µs



ELECTRICAL OPERATING CHARACTERISTICS (contined)

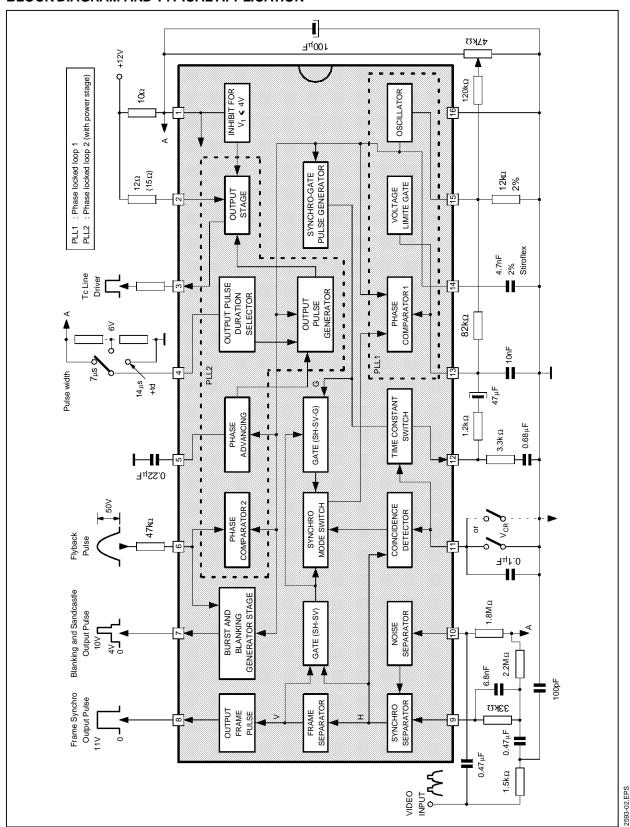
 $(T_{amb} = 25^{\circ}C, V_1-V_{16} = 12V, unless otherwise specified)$

Symbol	Parameter	Min.	Тур.	Max.	Unit
OVERALL PI	HASE RELATION SHIP	•		•	•
t _z	Phrase Between Middle Synchro Pulse and Middle Fly-back Pulse (t_r = 12 μ s, note 4	1.9		3.3	μs
ΔΙ/Δt	Sensitivity to Current Adjust		30		μΑ/μs
DSCILLATOR	R (PINS 14 AND 15)				
V ₁₄₋₁₆	Threshold Voltage (low level) (high level)		4.4 7.6		V
I ₁₄	Current Generator		± 0.47		mA
f	Free Running Frequency ($C_{osc} = 4700pF$, $R_{osc} = 12k\Omega$)		15625		Hz
Δf	Tolerance on Frequency (note 5)			± 5	%
Δf/15	Frequence Control Sensitivity		31		Hz/μA
Δf	Spread of Frequency		± 10		%
Δf/f	nfluence of Supply Voltage on Frequency (note 5)			± 0.05	%
Δ V/V nom.					
Δf	Frequency change when decreasing the supply down to 5 V $(V_{1-16} = 5V, note 5)$			± 10	%
T	Frequency Temperature Coefficient (note 5)			± 10 ⁻⁴	Hz/°C
PHASE COM	IPARATOR ø 1 (PIN 13)				
V _{13–16}	Control Voltage Range		3.8 to 8.2		V
I ₁₃	Control Current (peak value)		±1.9 to ±2.3		mA
I ₁₃	Off-state Current (V _{13–16} = 4 to 8 V)			– 1	μΑ
R ₁₃	Output Impedance $(V_{13-16} = 4 \text{ to } 8 \text{ V}, \text{ note } 6)$ $(V_{13-16} < 3.8 \text{ V cr} > 8.2 \text{ V}, \text{ note } 7)$		High Low		·
	Control Sensibility		2		kHz/μ
Δf	Catching and Holding Range		± 780		Hz
∆f/f	Catching and Holding Range Tolerance (note 5)		± 10		%
PHASE COM	IPARATOR φ 2 AND PHASE-SHIFT (PIN 5)				
V _{5–16}	Control Voltage Range		5.4 to 7.6		V
l ₅	Control Current (peak value)		± 1		mA
l ₅	Off-state Output Current (V ₅₋₁₆ = 5.4 to 7.6 V)			- 5	μА
R ₅	Output Impedance $(V_{5-16} = 5.4 \text{ to } 7.6 \text{ V}, \text{ note } 6)$ $(V_{5-16} < 5.4 \text{ V or } > 7.6 \text{ V})$		High 8		kΩ
t _d	Max. delay Between Output Pulse Leading Edge and Fly-back Pulse Trailing Edge (t _r = 12 μs)			15	μs
$\Delta_{t}/\Delta t_{d}$	Static Control Error			0.2	%
COÏNCIDEN	CE DETECTOR (PIN 11)				
V _{11–16}	Output Voltage		0.5 to 6		V
I ₁₁	Output Current (without coïncidence)		0.1		mA
	(with coïncidence)		- 0.5		mA
TIME CONST	FANT SWITCH (PIN 12)				
V ₁₂₋₁₆	Output Voltage		6		V
I ₁₂	Output Current		± 1		mA
R ₁₂	Output Impedance (V ₁₁₋₁₆ = 2.5 to 7 V) (V ₁₁₋₁₆ < 1.5 or > 9 V)		100 60		Ω kΩ
PULSE GEN	ERATOR (INTERNAL)				
t	Pulse Width		7.5		μs

Notes: 4. The adjustement of overall phase relation (and output pulse leading edge position) is automatically performed by phase comparator Ø 2. If additional adjustement is needed, a current have to be imposed at pin 5.

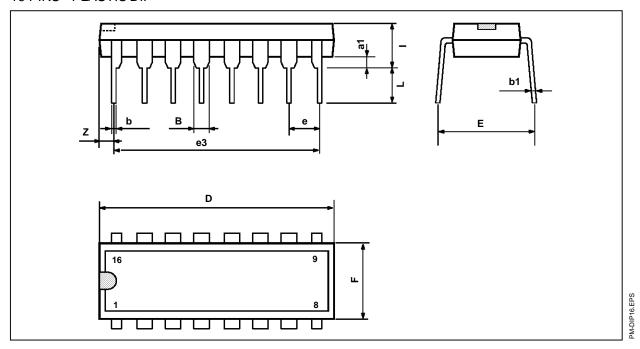
5. Tolerance of peripheral components not included.
6. Current generator.
7. Emitter-follower

BLOCK DIAGRAM AND TYPICAL APPLICATION



PACKAGE MECHANICAL DATA

16 PINS - PLASTIC DIP



Dimensions		Millimeters			Inches	
Difficusions	Min.	Тур.	Max.	Min.	Тур.	Max.
a1	0.51			0.020		
В	0.77		1.65	0.030		0.065
b		0.5			0.020	
b1		0.25			0.010	
D			20			0.787
E		8.5			0.335	
е		2.54			0.100	
e3		17.78			0.700	
F			7.1			0.280
i			5.1			0.201
L		3.3			0.130	
Z			1.27			0.050

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